

LARGE DEVIATION PROBABILITIES
FOR SUMS OF HEAVY-TAILED
DEPENDENT RANDOM VECTORS*

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ABSTRACT

Necessary and sufficient conditions are given for multidimensional p -stable limit theorems (i.e. theorems on convergence of normalized partial sums S_n/b_n of a stationary sequence of random vectors to a non-degenerate strictly p -stable limiting law μ , with $1/p$ -regularly varying normalizing sequence b_n). It is proved that similarly as in the one-dimensional case the conditions for $0 < p < 2$ consist of two parts: one responsible for (very weak) mixing properties and another, describing asymptotics of probabilities of large deviations (with a minor additional condition for $p = 1$). The paper focuses on effective methods of proving such large deviation results.

KEY WORDS AND PHRASES: multivariate stable distributions, regular variation, stable limit theorems, large deviations, stationary sequences, ψ -mixing, ϕ -mixing, m -dependence.

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1. A MULTIDIMENSIONAL STABLE LIMIT THEOREM

Let X_1, X_2, \dots be a stationary sequence of d -dimensional random vectors with partial sums $S_0 = 0$, $S_n = \sum_{j=1}^n X_j$. Following Jakubowski (1993) we will say that a p -stable limit theorem holds for $\{X_j\}$ if there exist a non-degenerate strictly p -stable law μ on \mathbb{R}^d and a $1/p$ -regularly varying sequence b_n , such that

$$\frac{S_n}{b_n} \xrightarrow{\mathcal{D}} \mu, \quad \text{as } n \rightarrow +\infty. \quad (1)$$

Recall that a p -stable law μ is *strictly* stable if for all $a, b > 0$ one can find $c = c(a, b) > 0$ such that $(\mu \circ R_a^{-1}) * (\mu \circ R_b^{-1}) = \mu \circ R_c^{-1}$, where for $a > 0$, $R_a(x) = a \cdot x$ is a rescaling of \mathbb{R}^d . For the case $p \neq 1, 2$, the logarithm $\log \hat{\mu}(y)$ of the characteristic function of a strictly p -stable law can be written in the form

$$\eta_p \int_{\{s \in S^{d-1}; \langle y, s \rangle > 0\}} |\langle y, s \rangle|^p \kappa(ds) + \bar{\eta}_p \int_{\{s \in S^{d-1}; \langle y, s \rangle < 0\}} |\langle y, s \rangle|^p \kappa(ds), \quad (2)$$

where $y \in \mathbb{R}^d$, S^{d-1} is the $d - 1$ -dimensional unit sphere in \mathbb{R}^d , κ is a finite Borel measure on S^{d-1} and

$$\eta_p = \begin{cases} \int_0^\infty (e^{iu} - 1) u^{-(1+p)} du & \text{if } 0 < p < 1, \\ \int_0^\infty (e^{iu} - 1 - iu) u^{-(1+p)} du & \text{if } 1 < p < 2. \end{cases} \quad (3)$$

For $p = 1$, a law μ is strictly stable if it is a shift of a *symmetric* strictly stable law with logarithm of the characteristic function of the form

$$-(1/2)\pi \int_{S^{d-1}} |\langle y, s \rangle| \kappa(ds), \quad (4)$$

where κ is a *symmetric* measure on S^{d-1} . Let us denote by $\text{Stab}(p, \kappa)$ the strictly stable law with logarithm of the characteristic function given by formulas (2) or (4). For more information on stable laws and processes we refer to Samorodnitsky and Taqqu (1994).

For random variables ($d = 1$) Jakubowski (1993, 1997) obtained necessary and sufficient conditions for a p -stable limit theorem to hold. In the case of *heavy-tailed* random variables (i.e. if $0 < p < 2$) the conditions essentially consist of two parts: a part responsible for “mixing” properties (Condition B_1 below) and a part describing asymptotic behaviour of probabilities of large deviations (Condition LD_1 below). In both cases subscript 1 stands for the dimension $d = 1$. Formal statements are as follows.

- **Condition B_1 .** For each $\lambda \in \mathbb{R}^1$, and as $n \rightarrow +\infty$

$$\max_{\substack{1 \leq k, l \leq n \\ k+l \leq n}} |E e^{i\lambda(S_{k+l}/b_n)} - E e^{i\lambda(S_k/b_n)} \cdot E e^{i\lambda(S_l/b_n)}| \longrightarrow 0. \quad (5)$$

- **Condition LD_1 .** There exists a sequence $r_n \rightarrow +\infty$ such that for all sequences x_n increasing to $+\infty$ *slowly enough* (i.e. $x_n = o(r_n)$)

$$x_n^p P(S_n/b_n > x_n) \longrightarrow c_+, \quad x_n^p P(S_n/b_n < -x_n) \longrightarrow c_-, \quad (6)$$

where $0 < c_+ + c_- < +\infty$ and $b_n \rightarrow +\infty$.

The relations between Conditions B_1 and LD_1 and p -stable limit theorems are particularly appealing in the case $p \neq 1$, as the following theorem shows (see Jakubowski, 1993 for the case $0 < p < 1$ and 1997 for the case $1 < p < 2$).

Theorem 1 *Let $0 < p < 1$ or $1 < p < 2$. Suppose Conditions B_1 and LD_1 hold with $b_n \rightarrow +\infty$ and $0 < c_+ + c_- < +\infty$. Then b_n varies $1/p$ -regularly and as $n \rightarrow +\infty$*

$$\frac{S_n}{b_n} \xrightarrow{\mathcal{D}} \text{Stab}(p, \kappa_{(c_+, c_-)}), \quad (7)$$

where $\kappa_{(c_+, c_-)}\{+1\} = c_+$ and $\kappa_{(c_+, c_-)}\{-1\} = c_-$.

Conversely, (7) with $c_+ + c_- > 0$ and $1/p$ -regular variation of b_n imply Conditions B_1 and LD_1 .

Notice that for $d = 1$ we have $S^{d-1} = S^0 = \{-1, +1\}$.

For $p = 1$ a minor additional assumption on centering is necessary (see Theorem 2.2, Jakubowski, 1997), which is automatically satisfied, when the S_n 's are symmetric:

Theorem 2 *If $p = 1$ and for each $n \in \mathbb{N}$, the law of S_n is symmetric, then Condition B_1 and Condition LD_1 with $0 < c_+ = c_- = c < +\infty$ hold if, and only if,*

$$\frac{S_n}{b_n} \xrightarrow{\mathcal{D}} \text{Stab}(1, \kappa_{(c,c)}), \quad \text{as } n \rightarrow +\infty, \quad (8)$$

where $0 < c < +\infty$ and b_n is regularly varying with exponent 1.

The purpose of the present note is to prove a multidimensional generalization of the above results.

Let us begin with introducing a multidimensional version of Condition B_1 .

• **Condition B_d .** For each $y \in \mathbb{R}^d$, and as $n \rightarrow +\infty$

$$\max_{\substack{1 \leq k, l \leq n \\ k+l \leq n}} |E e^{i\langle y, S_{k+l}/b_n \rangle} - E e^{i\langle y, S_k/b_n \rangle} \cdot E e^{i\langle y, S_l/b_n \rangle}| \longrightarrow 0. \quad (9)$$

Condition B_d describes a kind of “asymptotic independence” of partial sums. It is however essentially weaker than mixing conditions (such as α -mixing) usually considered in limit theory for sums, for there exist non-ergodic sequences satisfying (9). On the other hand Condition B_d held for *each* $y \in \mathbb{R}^d$ implies (under mild additional assumptions) *uniform convergence* over bounded subsets of \mathbb{R}^d :

$$\max_{\substack{1 \leq k, l \leq n \\ k+l \leq n}} \sup_{\|y\| \leq K} |E e^{i\langle y, S_{k+l}/b_n \rangle} - E e^{i\langle y, S_k/b_n \rangle} \cdot E e^{i\langle y, S_l/b_n \rangle}| \longrightarrow 0, \quad (10)$$

for every $K > 0$ and as $n \rightarrow +\infty$. In particular, (10) implies that given Condition B_d for *some* normalizing sequence $\{b_n\}$, we obtain it for *all* sequences b'_n such that $b_n \leq Cb'_n, n \in \mathbb{N}$, for some

constant $C > 0$. This has been observed by Szewczak (1996). For examples of sequences satisfying Condition B_d and further discussion in the case $d = 1$ (which can be easily extended to several dimensions) we refer to Jakubowski (1991,1993).

The form of Condition LD_d is somewhat more complicated than (6) and involves convergence to a measure which is, in general, finite only outside of every neighborhood of $0 \in \mathbb{R}^d$ (hence σ -finite). In our theorems such measures will always be Lévy measures, but from the point of view of sufficiency of Condition LD_d it is reasonable to formulate this condition in full generality.

For further purposes, let us denote by $\nu(p, \kappa)$ the Lévy measure of the infinite divisible law $\text{Stab}(p, \kappa)$. This means that for “radial” sets A of the form $A = \cup_{x \in B} x \cdot V$, where $B \in \mathcal{B}_{\mathbb{R}^+}$ and $V \in \mathcal{B}_{S^{d-1}}$, we have

$$\nu(p, \kappa)(A) = \int_B u^{-1-p} du \cdot \kappa(V). \quad (11)$$

Clearly, $\nu(p, \kappa) = 0$ if, and only if, $\kappa = 0$ and $\nu(p, \kappa)$ is symmetric if, and only if, κ is symmetric.

- **Condition LD_d .** There exists a sequence $b_n \rightarrow +\infty$ and a measure ν on \mathbb{R}^d , finite outside of every neighborhood of $0 \in \mathbb{R}^d$, such that for all sequences $x_n \rightarrow +\infty$ increasing “slowly enough” (i.e. $x_n = o(r_n)$ for some sequence $r_n \rightarrow +\infty$) we have

$$x_n^p P(S_n/b_n \in x_n A) \longrightarrow \nu(A), \quad (12)$$

whenever $A \in \mathcal{B}^d$, $\bar{A} \not\ni 0$ and $\nu(\partial A) = 0$.

Given Conditions B_d and LD_d we have a complete generalization of Theorems 1 and 2.

Theorem 3 *Let $0 < p < 1$ or $1 < p < 2$. Suppose Conditions B_d and LD_d hold with $b_n \rightarrow +\infty$ and $\nu \neq 0$.*

Then b_n varies $1/p$ -regularly, $\nu = \nu(p, \kappa)$ for some $\kappa \neq 0$ and

$$\frac{S_n}{b_n} \xrightarrow{\mathcal{D}} \text{Stab}(p, \kappa), \quad \text{as } n \rightarrow +\infty. \quad (13)$$

Conversely, (13) with $\kappa \neq 0$ and $1/p$ -regular variation of b_n imply Conditions B_d and LD_d with $\nu = \nu(p, \kappa)$.

Theorem 4 Let $p = 1$. Suppose for each $n \in \mathbb{N}$, the law of S_n is symmetric. Then Condition B_d and Condition LD_d with symmetric $\nu = \nu(1, \kappa) \neq 0$ hold if, and only if,

$$\frac{S_n}{b_n} \xrightarrow{\mathcal{D}} \text{Stab}(1, \kappa), \quad \text{as } n \rightarrow +\infty, \quad (14)$$

where $\kappa \neq 0$ is symmetric and b_n is regularly varying with exponent 1.

PROOF. NECESSITY OF CONDITION LD_d . In order to prove Condition LD_d we shall proceed similarly as in the one-dimensional case.

Let for each n , $Y_{n,1}, Y_{n,2}, \dots$ be independent copies of S_n/b_n . By strict stability of μ ,

$$k^{-1/p} \sum_{j=1}^k Y_{n,j} \xrightarrow{\mathcal{D}} \mu, \quad \text{as } n \rightarrow +\infty, \quad k = 1, 2, \dots \quad (15)$$

It follows that there exists $r_n \nearrow +\infty$ such, that for every sequence $\{k_n\} \subset \mathbb{N}$, which is increasing to infinity *slowly enough*, i.e., $k_n \rightarrow +\infty$, $k_n = o(r_n)$, we have

$$k_n^{-1/p} \sum_{j=1}^{k_n} Y_{n,j} \xrightarrow{\mathcal{D}} \mu, \quad \text{as } n \rightarrow +\infty. \quad (16)$$

(Notice that condition (16) is considerably weaker than condition (15)).

Since $k_n \rightarrow \infty$, the array $\{k_n^{-1/p} Y_{n,j}\}$ of row-wise independent random variables is infinitesimal and we can apply a convergence criterion for stable laws for sums of independent random variables. In particular, for each Borel subset $A \in \mathcal{B}^d$ which is separated from zero and such that $\nu(\partial A) = 0$, we have as $n \rightarrow +\infty$

$$k_n P(S_n/(b_n k_n^{1/p}) \in A) = k_n P(S_n/b_n \in k_n^{1/p} \cdot A) \longrightarrow \nu(A), \quad (17)$$

where $\nu = \nu(p, \kappa)$ is the Lévy measure of the stable law μ .

Setting $x_n = k_n^{1/p}$ we obtain Condition LD_d with sequences x_n of specific form and with rate $r_n^{1/p}$. Due to the special form of the Lévy measure $\nu(p, \kappa)$ we can extend (17) to all sequences $x_n \rightarrow +\infty$, $x_n = o(r_n^{1/p})$.

NECESSITY OF CONDITION B_d . Let $y \in \mathbb{R}^d$. Then

$$\langle y, S_n/b_n \rangle \xrightarrow{\mathcal{D}} \mu_y,$$

where μ_y is the strictly stable law on \mathbb{R}^d being an image of μ under the mapping $\mathbb{R}^d \ni x \mapsto \langle y, x \rangle \in \mathbb{R}^1$. If $y \in \mathbb{R}^d$ is such that μ_y is different from δ_0 , we obtain (9) from the corresponding theorem for $d = 1$. If $\mu_y = \delta_0$, we have for any sequence $k_n \leq n$

$$\left\langle y, \frac{S_{k_n}}{b_n} \right\rangle = \frac{b_{k_n}}{b_n} \cdot \left\langle y, \frac{S_{k_n}}{b_{k_n}} \right\rangle \xrightarrow{\mathcal{P}} 0,$$

for if $k_{n'} \rightarrow \infty$ along some subsequence n' , then $\sup_n b_{k_n}/b_n < +\infty$ by regular variation of b_n and if $k_{n''}$ remains bounded along some subsequence n'' , then we have $b_{k_{n''}}/b_{n''} \rightarrow 0$ by $b_n \rightarrow \infty$. Hence if $k_n + l_n \leq n$, then $S_{k_n+l_n}/b_n \xrightarrow{\mathcal{P}} 0$, $S_{k_n}/b_n \xrightarrow{\mathcal{P}} 0$ and $S_{l_n}/b_n \xrightarrow{\mathcal{P}} 0$ and (9) is satisfied for y , too.

SUFFICIENCY. Suppose Conditions B_d and LD_d hold for some $b_n \rightarrow \infty$ and some measure ν which is finite outside of every neighborhood of $0 \in \mathbb{R}^d$. Since strict stability of μ is equivalent to $\mu^{*n} = \mu \circ R_{n^{1/p}}^{-1}$ for each $n \in \mathbb{N}$, it is sufficient to prove that for each $y \in \mathbb{R}^d$ one dimensional sums $\sum_{k=1}^n \langle y, X_k/b_n \rangle$ converge to *some* strictly p -stable law on \mathbb{R}^1 (possibly degenerated at 0).

Let us fix $y \in \mathbb{R}^d$, $y \neq 0$, and consider in (12) the following sets $A_+^y, A_-^y \subset \mathbb{R}^d$

$$A_+^y = \{x; \langle y, x \rangle > 1\}, \quad A_-^y = \{x; \langle y, x \rangle < -1\}. \quad (18)$$

These sets are separated from zero and we may assume that $\nu(\partial A_{\pm}^y) = 0$ (otherwise we may replace y with $r \cdot y$ for some

$1 > r > 0$). Moreover, by (12) we have

$$x_n^p P \left(\sum_{k=1}^n \langle y, X_k/b_n \rangle > x_n \right) = x_n^p P (S_n/b_n \in x_n A_+^y) \rightarrow c_+ = \nu(A_+^y),$$

provided $x_n \rightarrow +\infty$ slowly enough. Similar relation holds for the left-hand tails of $\sum_{k=1}^n \langle y, X_k/b_n \rangle$. It follows that in the case

$$\nu(A_+^y) + \nu(A_-^y) > 0 \quad (19)$$

we may apply either Theorem 1 (for $0 < p < 1$ and $1 < p < 2$) or Theorem 2 (for $p = 1$) in order to get the convergence of $\{\sum_{k=1}^n \langle y, X_k/b_n \rangle\}$ to a non-degenerate strictly p -stable law. In particular, b_n is p -regularly varying for there are y 's satisfying (19) (by $\nu \neq 0$).

It remains to prove that regular p -variation of b_n and $\nu(A_+) + \nu(A_-) = 0$ imply

$$\sum_{k=1}^n \langle y, X_k/b_n \rangle \xrightarrow{\mathcal{P}} 0. \quad (20)$$

This can be done in various ways. One can use, for example the normal convergence criterion (with the limit $\delta_0 = \mathcal{N}(0, 0)$) developed in Jakubowski and Szewczak (1991) together with the estimates of truncated moments given in Denker and Jakubowski (1989). Less formal is the following procedure. Take $\{Y_k^c\}$ to be independent, identically distributed and such that

$$\sum_{k=1}^n Y_k^c/b_n \xrightarrow{\mathcal{D}} \text{Stab}(p, \kappa_{(c,c)}),$$

where $\kappa_{(c,c)}$ is the same as in (7). By the corresponding one-dimensional theorem, we have for x_n increasing slowly enough

$$x_n^p P \left(\sum_{k=1}^n Y_k^c/b_n > x_n \right) \rightarrow c,$$

as well as

$$x_n^p P \left(\sum_{k=1}^n Y_k^c/b_n < -x_n \right) \rightarrow c.$$

It is now a matter of simple manipulations to deduce that we have also

$$x_n^p P \left(\sum_{k=1}^n (Y_k^c + \langle y, X_k \rangle) / b_n > x_n \right) \rightarrow c,$$

(and similarly for the left-hand tails). Since Condition B_1 is obviously satisfied for the sequence $\{Y_k^c + \langle y, X_k \rangle\}$, we obtain

$$\sum_{k=1}^n (Y_k^c + \langle y, X_k \rangle) / b_n \xrightarrow{\mathcal{D}} \text{Stab}(p, \kappa_{(c,c)}).$$

Letting $c \searrow 0$ we obtain (20). \square

2. PROBABILITIES OF LARGE DEVIATIONS IN \mathbb{R}^d

It follows from the proof of Theorems 3 and 4 that instead of Condition LD_d as it stands in (12) one can restrict the attention to verifying whether

$$x_n^p P(S_n / b_n \in x_n A) \longrightarrow \nu(A), \quad (21)$$

for much smaller class of sets $A \in \mathcal{B}^d$ than the whole ring of bounded away from zero sets of ν -continuity. For example it is enough to consider sets A_{\pm}^y , $y \in \mathbb{R}^d$, defined by (18) or “radial” sets described in (11). However, the problem does not seem to be easier after simplification of such kind.

Fortunately, there are methods of essential reduction of (21) to problems depending on properties of joint distributions of a *fixed* finite number of random variables X_1, X_2, \dots, X_m . These methods were discussed in great detail in Jakubowski (1997) for the case $d = 1$. Here we shall describe only basic steps in derivation of their multidimensional versions.

In all considerations the following generalization of the well-known Bonferroni’s inequality is crucial.

Lemma 5 (*Lemma 3.2, Jakubowski, 1997*). Let Z_1, Z_2, \dots be stationary random vectors taking values in a linear space (E, \mathcal{B}_E) . Set $T_0 = 0$, $T_m = \sum_{j=1}^m Z_j$, $m \in \mathbb{N}$. If $U \in \mathcal{B}_E$ is such that $0 \notin U$, then for every $n \in \mathbb{N}$ and every $k \in \mathbb{N}$, $k \leq n$, the following inequality holds:

$$\begin{aligned} & |P(T_n \in U) - n(P(T_{k+1} \in U) - P(T_k \in U))| \\ & \leq 3kP(Z_1 \neq 0) + 2 \sum_{\substack{1 \leq i < j \leq n \\ j-i > k}} P(Z_i \neq 0, Z_j \neq 0). \end{aligned} \quad (22)$$

To be applied effectively, inequality (22) requires that random vectors Z_n with great probability take value 0 and that clusters of nonzero values are essentially of short length (i.e. of size k). This can be achieved by subtracting from X_k/b_n their truncation around origin (in such a way that the total sum S_n/b_n is little perturbed - typical property of heavy-tailed random elements), and imposing mixing conditions which guarantee a kind of asymptotic independence of remaining “big” parts of components. The whole procedure is laborious and completely analogous to the one-dimensional case, hence we refer to Jakubowski (1997) for details.

We shall consider three cases of particular interest: ψ -mixing, m -dependent and ϕ -mixing sequences (for definitions see Bradley and Bryc, 1985, or Jakubowski, 1993) satisfying the following “usual conditions”:

U0. X_1, X_2, \dots are strictly stationary random vectors.

U1. $\{b_n\}$ is a $1/p$ -regularly varying sequence for some p , $0 < p < 2$.

U2. For some $K_0 < +\infty$

$$\sup_{n \in \mathbb{N}} \sup_{x > 0} x^p \cdot n \cdot P(\|X_1\| > x \cdot b_n) \leq K_0. \quad (23)$$

U3. If $p = 1$, then the law of X_1 , $\mathcal{L}(X_1)$, is symmetric.

U4. If $1 < p < 2$, then $EX_1 = 0$.

Theorem 6 *Suppose $\{X_k\}$ is exponentially ψ -mixing (i.e. $\psi(n) \leq K\eta^n$, $n = 1, 2, \dots$, for some $K > 0$ and $0 < \eta < 1$), and such that*

$$\psi(1) < +\infty. \quad (24)$$

Then for all x_n increasing slowly enough, as $n \rightarrow +\infty$,

$$x_n^p |P(S_n/b_n \in x_n A) - nP(X_1/b_n \in x_n A)| \rightarrow 0, \quad (25)$$

for all $A \in \mathcal{B}^d$, $\bar{A} \not\equiv 0$. In particular, $nP(X_1 \in b_n \cdot A) \rightarrow \nu(A)$ implies

$$x_n^p P(S_n/b_n \in x_n A) \rightarrow \nu(A). \quad (26)$$

Theorem 7 *Let $\{X_k\}$ be m -dependent. Then for all x_n increasing slowly enough*

$$x_n^p |P(S_n/b_n \in x_n A) \quad (27)$$

$$-n (P(S_{m+1}/b_n \in x_n \cdot A) - P(S_m/b_n \in x_n \cdot A))| \rightarrow 0,$$

for all $A \in \mathcal{B}^d$, $\bar{A} \not\equiv 0$. In particular, if

$$n (P(S_{m+1} \in b_n \cdot A) - P(S_m \in b_n \cdot A)) \rightarrow \nu(A), \quad (28)$$

as $n \rightarrow +\infty$, then

$$x_n^p P(S_n/b_n \in x_n A) \rightarrow \nu(A). \quad (29)$$

Theorem 8 *Suppose $\{X_k\}$ is exponentially ϕ -mixing. Then for all x_n increasing slowly enough*

$$\limsup_m \limsup_n x_n^p |P(S_n/b_n \in x_n A) \quad (30)$$

$$-n (P(S_{m+1}/b_n \in x_n \cdot A) - P(S_m/b_n \in x_n \cdot A))| = 0,$$

for all $A \in \mathcal{B}^d$, $\bar{A} \not\equiv 0$. In particular, if for each $m \in \mathbb{N}$ we have

$$nP(S_m \in b_n \cdot A) \rightarrow \nu_m(A) \quad (31)$$

and, as $m \rightarrow \infty$,

$$\nu_{m+1}(A) - \nu_m(A) \rightarrow \nu(A), \quad (32)$$

then

$$x_n^p P(S_n/b_n \in x_n A) \rightarrow \nu(A). \quad (33)$$

Remark 9 Theorems 6-8 can be used as tools for proving limit theorems based on Theorems 3 and 4. For example Theorem 6 leads to a result similar to that of Davis (1983) (obtained by purely one-dimensional methods). Theorem 7 allows proving results for m -dependent stationary random vectors due to Jakubowski and Kobus (1989) and Kobus (1995) (originally obtained by the point processes technique). Theorem 8 corresponds to Theorem 3.9 in Jakubowski (1997), and gives a counterpart to the early Ibragimov's central limit theorem (Ibragimov, 1962).

Remark 10 Let us notice that in formulas (27), (29) and (33) probabilities of large deviations “in direction” of the set A *does not* depend on values of random variables *outside* of the “direction” A . This fact is far from being obvious! In particular, in the list of “usual conditions” we did not assume regularity in all “directions” (U2 says that there is no “dominating direction”), and so the whole sum S_n/b_n may be divergent while Condition LD_d holds for some family of sets A .

Remark 11 In Davis and Hsing (1995), under less general conditions, an interesting probabilistic representation is given for constants c_+ and c_- appearing in Theorems 1 and 2. This representation is expressed in terms of functionals of certain point processes naturally associated with the sequence $\{X_k\}$. Since the structure of the multidimensional limit law is more complicated than in the case $d = 1$, it would be interesting to extend Davis and Hsing's results and explain the mechanism of generating the limiting Lévy measure in Condition LD_d .

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